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Simulation and Control with C# and WinForms

Hans-Petter Halvorsen

Contents

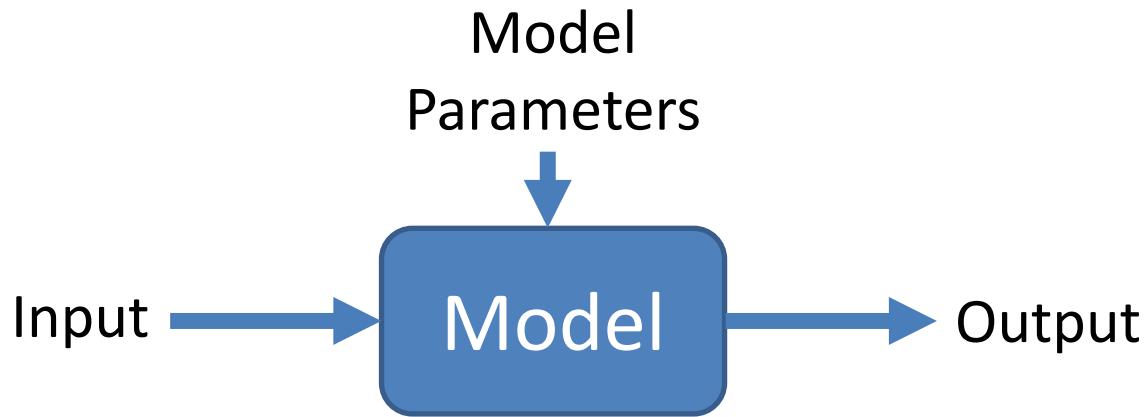
- What is a Model?
- C# WinForms Examples
- Timer
- Plotting
- Controller

Finally, we will end up with basic Control System, where we control a Dynamic System using a Mathematical Model

Audience

- This Tutorial is made for rookies making their first basic C# Win Forms Application
- You don't need any experience in either Visual Studio or C#
- No skills in Automation or Control System is necessary

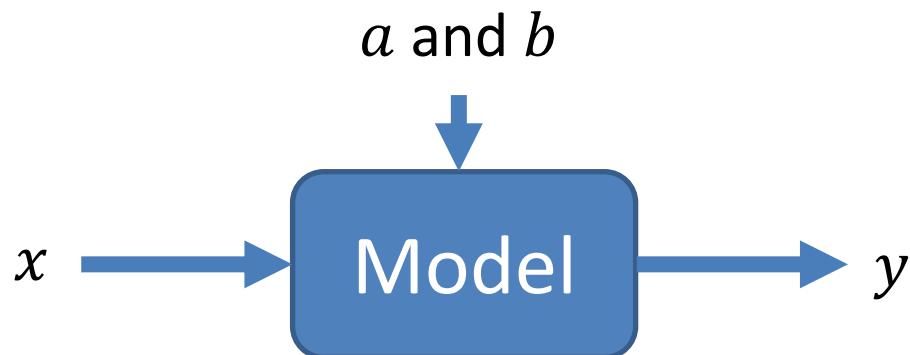
Model



Model Example

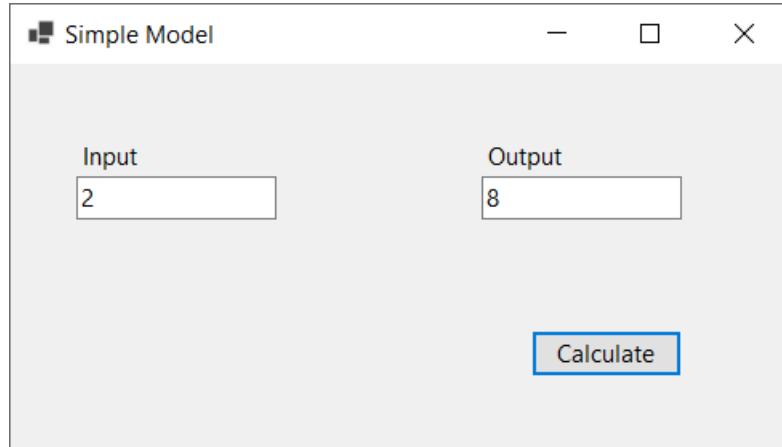
Simple Model: $y = ax + b$

This is 1. order linear model



WinForms App

$$y = ax + b$$



Example:

$$\begin{aligned} a &= 2 \\ b &= 4 \end{aligned}$$

$$y = 2x + 4$$

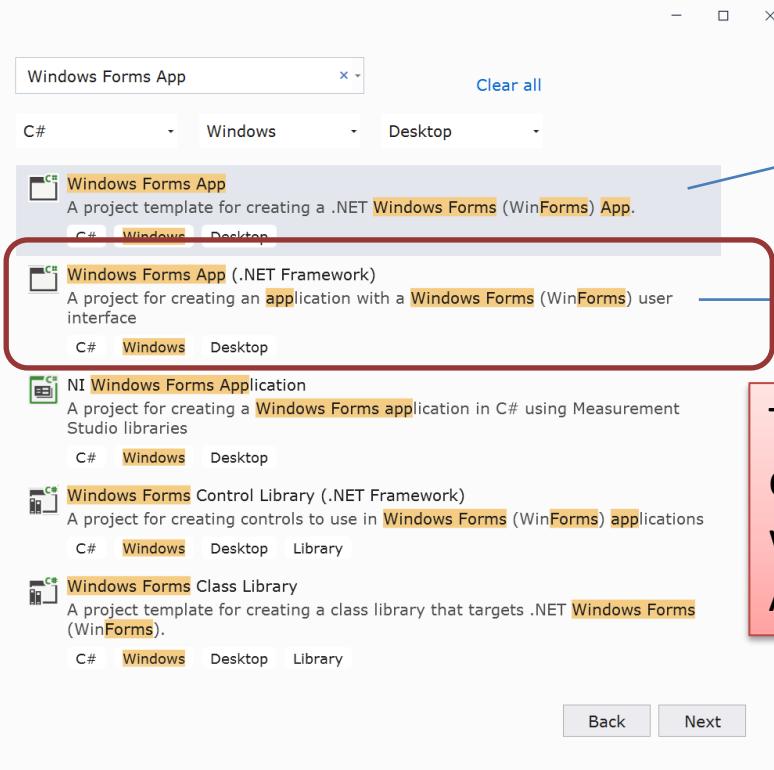
$$y(2) = 2 \cdot 2 + 4 = 8$$

Create Project

Create a new project

Recent project templates

- Windows Forms App (.NET Framework) C#
- Windows Forms App C#
- ASP.NET Core Web App C#
- Python Application Python



The Chart component so far does not exist for .NET 5, so we select “Windows Forms App (.NET Framework)”

C# Examples

Note!

- The examples provided can be considered as a “proof of concept”
- The sample code is very simplified for clarity and doesn't necessarily represent best practices.

Visual Studio Project

The screenshot shows the Microsoft Visual Studio IDE interface with a Windows Form application named "Simple Model" open. The application has two text boxes labeled "Input" and "Output" and a button labeled "Calculate".

Toolbox: Contains various Windows Forms controls such as PrintPreviewDialog, Process, ProgressBar, PropertyGrid, RadioButton, RichTextBox, SaveFileDialog, SplitContainer, Splitter, StatusStrip, TabControl, TableLayoutPanel, TextBox, Timer, ToolStrip, ToolTip, TrackBar, TreeView, VScrollBar, Containers, Menus & Toolbars, Components (Pointer, BackgroundWorker, ErrorProvider), and SQL Server Object Explorer.

Solution Explorer: Shows the solution "SimpleModel" with one project "SimpleModel" containing files "Form1.cs", "Form1.Designer.cs", "Form1.resx", and "Program.cs".

Error List: Displays 0 Errors, 0 Warnings, and 0 of 2 Messages.

Properties: Shows the properties for "Form1" of type "System.Windows.Forms.Form". The "Text" property is set to "Simple Model". The "Text" description is "The text associated with the control."

Notifications: Shows "Diagnostic Tools".

Status Bar: Shows "Ready", "208 , 209", and "0 x 0".

C# Code

```
using System;
using System.Windows.Forms;

namespace SimpleModel
{
    public partial class Form1 : Form
    {
        public Form1()
        {
            InitializeComponent();
        }

        private void btnCalculate_Click(object sender, EventArgs e)
        {
            double x, y;

            x = Convert.ToDouble(txtInput.Text);

            y = LinearModel(x);
            txtOutput.Text = y.ToString();
        }

        double LinearModel(double x)
        {
            double a = 2;
            double b = 4;
            double y;

            y = a * x + b;
            return y;
        }
    }
}
```

C# Code

```
double LinearModel(double x)
{
    double a = 2;
    double b = 4;
    double y;

    y = a * x + b;
    return y;
}
```

C# Code

```
private void btnCalculate_Click(object sender, EventArgs e)
{
    double x, y;

    x = Convert.ToDouble(txtInput.Text);

    y = LinearModel(x);

    txtOutput.Text = y.ToString();
}
```

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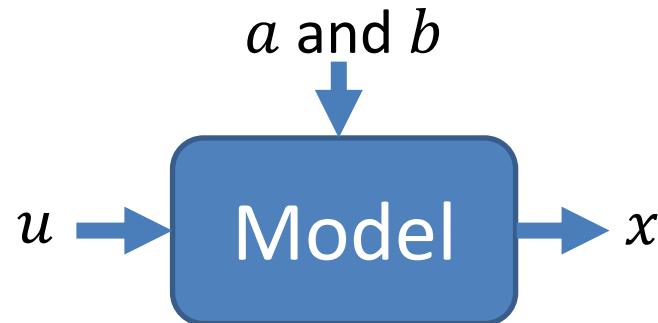
Simulations of Dynamic Systems

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Dynamic Model

In this example we will use the following 1. order differential equation:

$$\dot{x} = -ax + bu$$



Note that $\dot{x} = \frac{dx}{dt} = x'(t)$

Different notation is used in
different textbooks and examples

In order to simulate such model with C#, we need to find a **discrete** version

Discretization

- In order to simulate this system, we typically need to find the discrete differential equation (difference equation)
- We can use e.g., the **Euler** Approximation:

$$\dot{x} \approx \frac{x(k+1) - x(k)}{T_s}$$

Where T_s is the Sampling Time

Discrete Model

We have the continuous differential equation: $\dot{x} = -ax + bu$

We apply Euler: $\dot{x} \approx \frac{x(k+1) - x(k)}{T_s}$

Then we get:

$$\frac{x(k+1) - x(k)}{T_s} = -ax(k) + bu(k)$$

This gives the following discrete differential equation (difference equation):

$$x(k+1) = (1 - T_s a)x(k) + T_s b u(k)$$

This equation can easily be implemented in any text-based programming language

WinForms App

$$x(k + 1) = (1 - T_s a)x(k) + T_s b u(k)$$

The screenshot shows a Windows application window titled "Form1". Inside the window, there are two text boxes labeled "Input" and "Output". The "Input" box contains the number "1". The "Output" box contains the number "2.66". Below the input field is a blue-bordered button labeled "Calculate". The window has standard minimize, maximize, and close buttons at the top right.

Every time we click “Calculate”, a new updated value of $x(k + 1)$ is calculated

Example:

$$a = 0.25$$

$$b = 2$$

Visual Studio Project

The screenshot shows the Microsoft Visual Studio IDE interface with the following components:

- Menu Bar:** File, Edit, View, Project, Build, Debug, Format, Test, Analyze, Tools, Extensions, Window, Help.
- Toolbox:** Displays various Windows Forms controls including PrintPreviewControl, PrintPreviewDialog, Process, ProgressBar, PropertyGrid, RadioButton, RichTextBox, SaveFileDialog, SplitContainer, Splitter, StatusStrip, TabControl, TableLayoutPanel, TextBox, Timer, ToolStrip, ToolTip, TrackBar, TreeView, VScrollBar, Containers, Menus & Toolbars, Components, Pointer, BackgroundWorker, and ErrorProvider.
- Form Designer:** Shows a window titled "Form1" with an "Input" text box, an "Output" text box, and a "Calculate" button.
- Solution Explorer:** Shows a solution named "DiscreteModel" containing one project "DiscreteModel" which includes files Form1.cs, Form1.Designer.cs, Form1.resx, and Program.cs.
- Error List:** Shows 0 Errors and 0 Warnings.
- Properties:** Shows the properties for the "txtOutput" control, which is a System.Windows.Forms.TextBox. The properties listed are:

RightToLeft	No
ScrollBars	None
ShortcutsEnabled	True
Size	125, 27
TabIndex	6
Text	The text associated with the control.
- Toolbox:** Shows the SQL Server Object Explorer tab.
- Status Bar:** Ready, 298 , 65, 125 x 27, Add to Source Control, Notifications, Diagnostic Tools.

C# Code

```
using System;
using System.Windows.Forms;

namespace DiscreteModel
{
    public partial class Form1 : Form
    {
        double x = 0;
        double u=1;
        double Ts = 0.1;

        public Form1()
        {
            InitializeComponent();
            txtInput.Text = "1";
        }

        private void btnCalculate_Click(object sender, EventArgs e)
        {
            u = Convert.ToDouble(txtInput.Text);
            x = DiscreteModel(x, u);
            txtOutput.Text = x.ToString("0.##");
        }

        double DiscreteModel(double xk, double u)
        {
            double a = 0.25;
            double b = 2;
            double xk1;
            xk1 = (1-Ts*a) * xk + Ts*b*u;
            return xk1;
        }
    }
}
```

Discrete Model - C# Code

$$x(k + 1) = (1 - T_s a)x(k) + T_s b u(k)$$

```
double DiscreteModel (double xk, double u)
{
    double a = 0.25;
    double b = 2;
    double xk1;

    xk1 = (1-Ts*a) * xk + Ts*b*u;
    return xk1;
}
```

C# Code

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using System;
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            txtInput.Text = "1";
        }

        private void btnCalculate_Click(object sender, EventArgs e)
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        double DiscreteModel(double xk, double u)
        {
            double a = 0.25;
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            xk1 = (1-Ts*a) * xk + Ts*b*u;
            return xk1;
        }
    }
}
```

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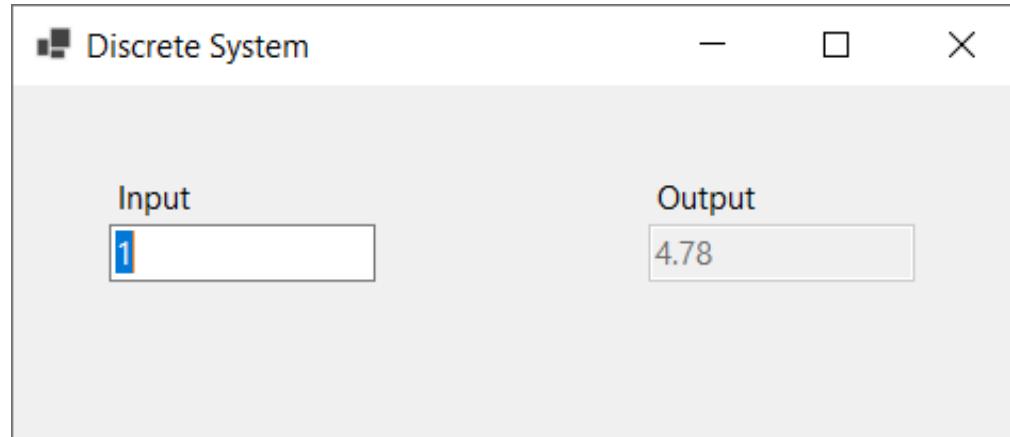


Using a Timer

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Timer

So far, we needed to push the “Calculate” Button in order to calculate a new updated value. We need to find a better solution, so we introduce and using a Timer



Here we have removed the button and using a Timer instead. A Timer is like a While Loop

Timer - C# Code

We move the code from the Button Event Handler to the Timer Event Handler:

```
private void timerSimulationLoop_Tick(object sender, EventArgs e)
{
    u = Convert.ToDouble(txtInput.Text);

    x = DiscreteModel(x, u);

    txtOutput.Text = x.ToString("0.##");
}
```

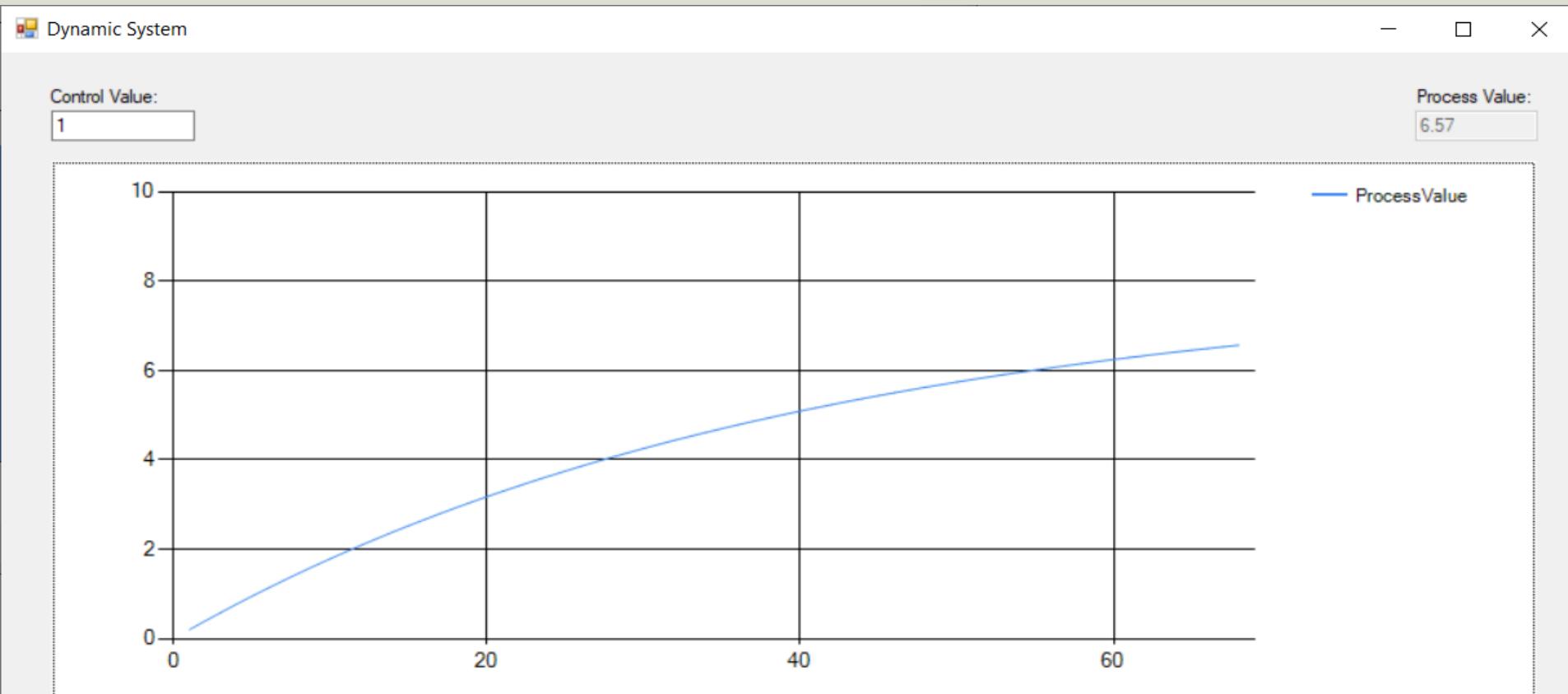
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Plotting

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WinForms App

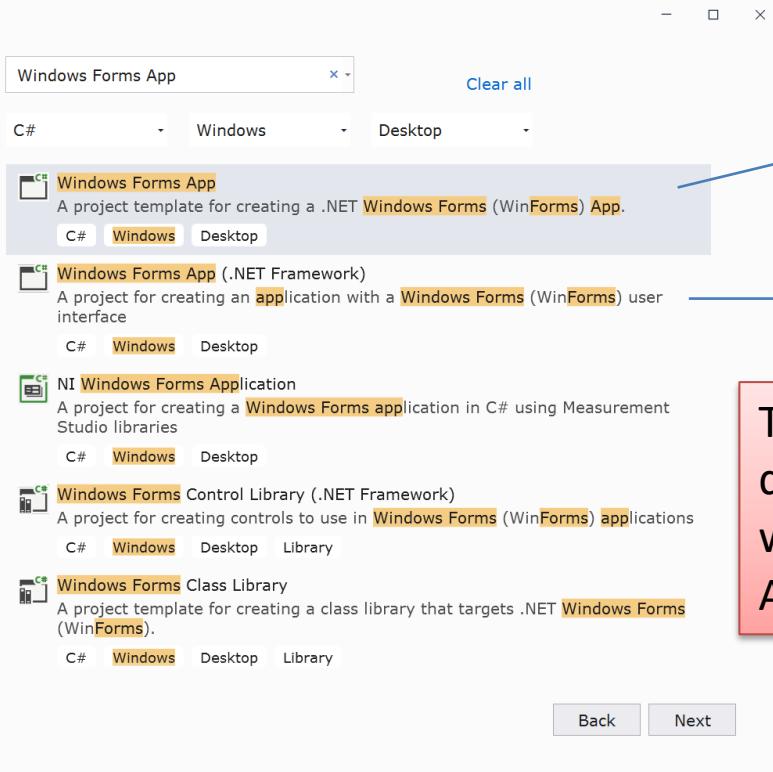


Create Project

Create a new project

Recent project templates

- Windows Forms App (.NET Framework) C#
- Windows Forms App C#
- ASP.NET Core Web App C#
- Python Application Python



New .NET 5

.NET Framework 4.x

The Chart component so far does not exist for .NET 5, so we select “Windows Forms App (.NET Framework)”

Create Project

- □ ×

Configure your new project

Windows Forms App (.NET Framework) C# Windows Desktop

Project name

DynamicSystem

Location

C:\Users\hansp\OneDrive\Programming\Visual Studio Examples



Solution name ⓘ

DynamicSystem

Place solution and project in the same directory

Framework

.NET Framework 4.8

Back

Create

Visual Studio Project

Screenshot of the Visual Studio IDE interface showing a Windows Forms application project named "DynamicSystem".

The main window displays a bar chart titled "Dynamic System" with "Control Value" and "Process Value" input fields. The chart has 8 bars representing values from 1 to 8.

Index	Control Value	Process Value
1	72	22
2	72	22
3	82	22
4	72	22
5	22	22
6	82	22
7	42	22
8	0	0

The Solution Explorer shows the project structure:

- Solution 'DynamicSystem' (1 item)
- DynamicSystem (Properties, References, App.config)
- Form1.cs (Form1.Designer.cs, Form1.resx)
- Program.cs

The Properties window shows the following settings for Form1:

- RightToLeft: No
- RightToLeftLayout: False
- ShowIcon: True
- ShowInTaskbar: True
- Size: 1321, 602
- SizeGripStyle: Auto
- StartPosition: WindowsDefault
- Tag: Dynamic System
- Text: Dynamic System
- TopMost: False

The Error List shows 0 errors, 0 warnings, and 0 messages.

C# Code

```
using System;
using System.Windows.Forms;
using System.Windows.Forms.DataVisualization.Charting;

namespace DynamicSystem
{
    public partial class Form1 : Form
    {
        double processValue = 0; double controlValue = 1; double Ts = 0.1;
        public Form1()
        {
            InitializeComponent();
            txtControlValue.Text = "1";

            chartMeasurementData.Series.Clear();
            chartMeasurementData.Series.Add("ProcessValue");
            chartMeasurementData.Series["ProcessValue"].ChartType = SeriesChartType.Line;
            ChartArea areal = chartMeasurementData.ChartAreas[0];
            areal.AxisY.Minimum = 0;
            areal.AxisY.Maximum = 10;

            timerSimulationLoop.Interval = 1000;
            timerSimulationLoop.Start();
        }

        double DiscreteModel(double xk, double u)
        {
            double a = 0.25; double b = 2; double xk1;
            xk1 = (1 - Ts * a) * xk + Ts * b * u;
            return xk1;
        }

        private void timerSimulationLoop_Tick(object sender, EventArgs e)
        {
            controlValue = Convert.ToDouble(txtControlValue.Text);
            processValue = DiscreteModel(processValue, controlValue);
            txtProcessValue.Text = processValue.ToString("0.##");
            chartMeasurementData.Series["ProcessValue"].Points.AddY(processValue);
        }
    }
}
```

Improvements

- Improve GUI
- Add Units
- Create and use a PID Controller
- Etc.

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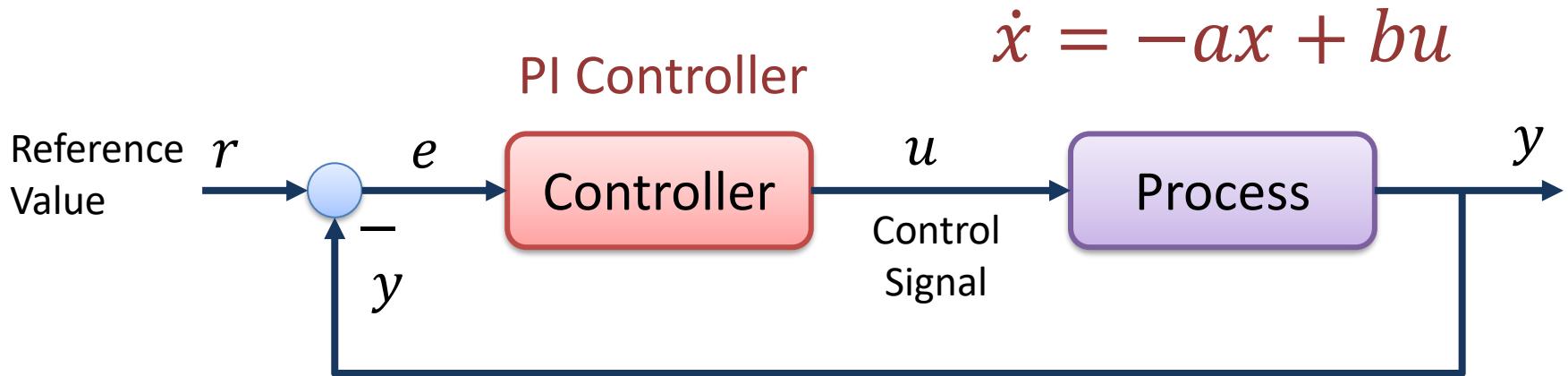
Controller

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Control System

- We have created and used a Mathematical Model
- Next step is to create a Control System
- We will implement a PI Controller

Control System



PI Controller

The PI Controller is given by:

$$u(t) = K_p e(t) + \frac{K_p}{T_i} \int_0^t e d\tau$$

Where u is the controller output and e is the control error:

$$e(t) = r(t) - y(t)$$

Where r is the reference signal (setpoint)

Or PI Controller on Transfer Function form (we use Laplace):

$$u(s) = K_p e(s) + \frac{K_p}{T_i s} e(s)$$

In order to implement the PI controller in our C# program, we need to make a discrete version

PI Controller

The PI Controller is given by:

$$u(s) = K_p e(s) + \frac{K_p}{T_i s} e(s)$$

We set $z = \frac{1}{s} e \Rightarrow sz = e \Rightarrow \dot{z} = e$

This gives:

$$\dot{z} = e$$

$$u = K_p e + \frac{K_p}{T_i} z$$

This is the PI controller on state-space form

Discrete PI Controller

Using Euler:

$$\dot{z} \approx \frac{z_{k+1} - z_k}{T_s}$$

Where T_s is the Sampling Time.

This gives:

$$\frac{z_{k+1} - z_k}{T_s} = e_k$$

$$u_k = K_p e_k + \frac{K_p}{T_i} z_k$$

Finally, we get the following discrete PI controller:

$$e_k = r_k - y_k$$

$$u_k = K_p e_k + \frac{K_p}{T_i} z_k$$

$$z_{k+1} = z_k + T_s e_k$$

This algorithm can easily be implemented in C#.

Control System Implementation

PI Controller

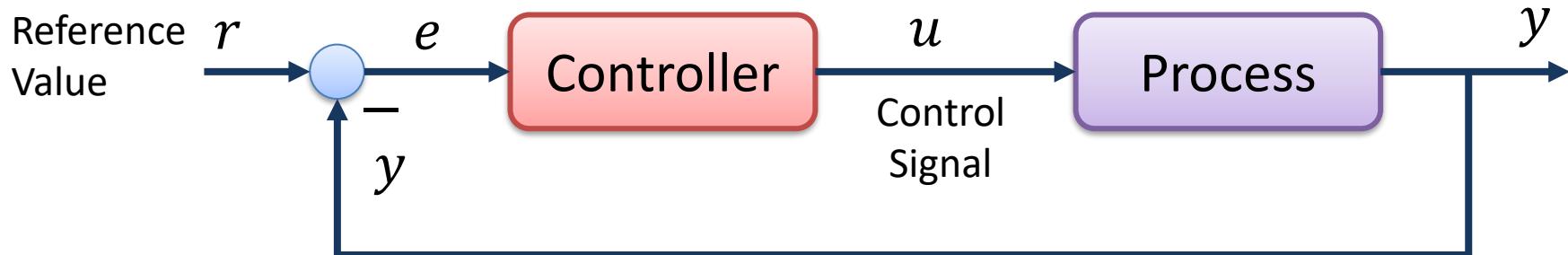
$$e_k = r_k - y_k$$

$$u_k = K_p e_k + \frac{K_p}{T_i} z_k$$

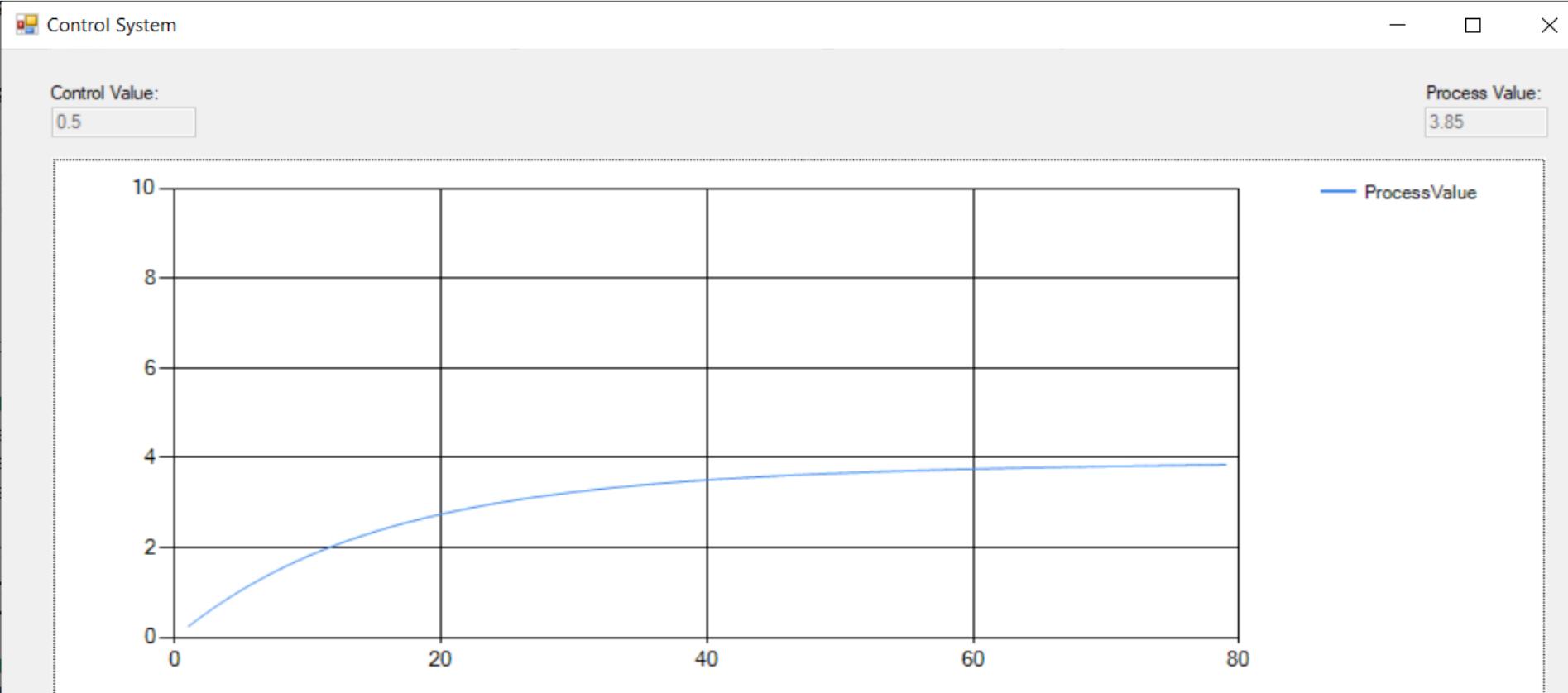
$$z_{k+1} = z_k + T_s e_k$$

Discrete Mathematical Model

$$x(k + 1) = (1 - T_s a)x(k) + T_s b u(k)$$



WinForms App



C# Code

```
using System;
using System.Windows.Forms;
using System.Windows.Forms.DataVisualization.Charting;

namespace DynamicSystem
{
    public partial class Form1 : Form
    {
        double processValue = 0; controlValue = 0;
        double Ts = 0.1;
        double Kp = 0.3; Ti = 5; r = 4;
        double u=0, z = 0;

        public Form1()
        {
            InitializeComponent();

            chartMeasurementData.Series.Clear();
            chartMeasurementData.Series.Add("ProcessValue");
            chartMeasurementData.Series["ProcessValue"].ChartType = SeriesChartType.Line;
            ChartArea areal = chartMeasurementData.ChartAreas[0];
            areal.AxisY.Minimum = 0; areal.AxisY.Maximum = 10;

            timerSimulationLoop.Interval = 1000;
            timerSimulationLoop.Start();
        }

        private void timerSimulationLoop_Tick(object sender, EventArgs e)
        {
            controlValue = PiController(processValue);
            processValue = DiscreteModel(processValue, controlValue);

            txtProcessValue.Text = processValue.ToString("0.##");
            txtControlValue.Text = controlValue.ToString("0.##");

            chartMeasurementData.Series["ProcessValue"].Points.AddY(processValue);
        }

        double DiscreteModel(double xk, double u)
        {
            double a = 0.25; double b = 2; double xk1;
            xk1 = (1 - Ts * a) * xk + Ts * b * u;
            return xk1;
        }

        double PiController(double y)
        {
            double e = r - y;
            u = Kp * e + (Kp / Ti) * z;
            z = z + Ts * e;
            return u;
        }
    }
}
```

C# Code

```
...  
  
namespace DynamicSystem  
{  
    public partial class Form1 : Form  
    {  
        double processValue = 0; controlValue = 0;  
        double Ts = 0.1;  
        double Kp = 0.3; Ti = 5; r = 4;  
        double u=0, z = 0;  
  
        ...  
  
        double PiController(double y)  
        {  
            double e = r - y;  
            u = Kp * e + (Kp / Ti) * z;  
            z = z + Ts * e;  
            return u;  
        }  
    }  
}
```

$$e_k = r_k - y_k$$

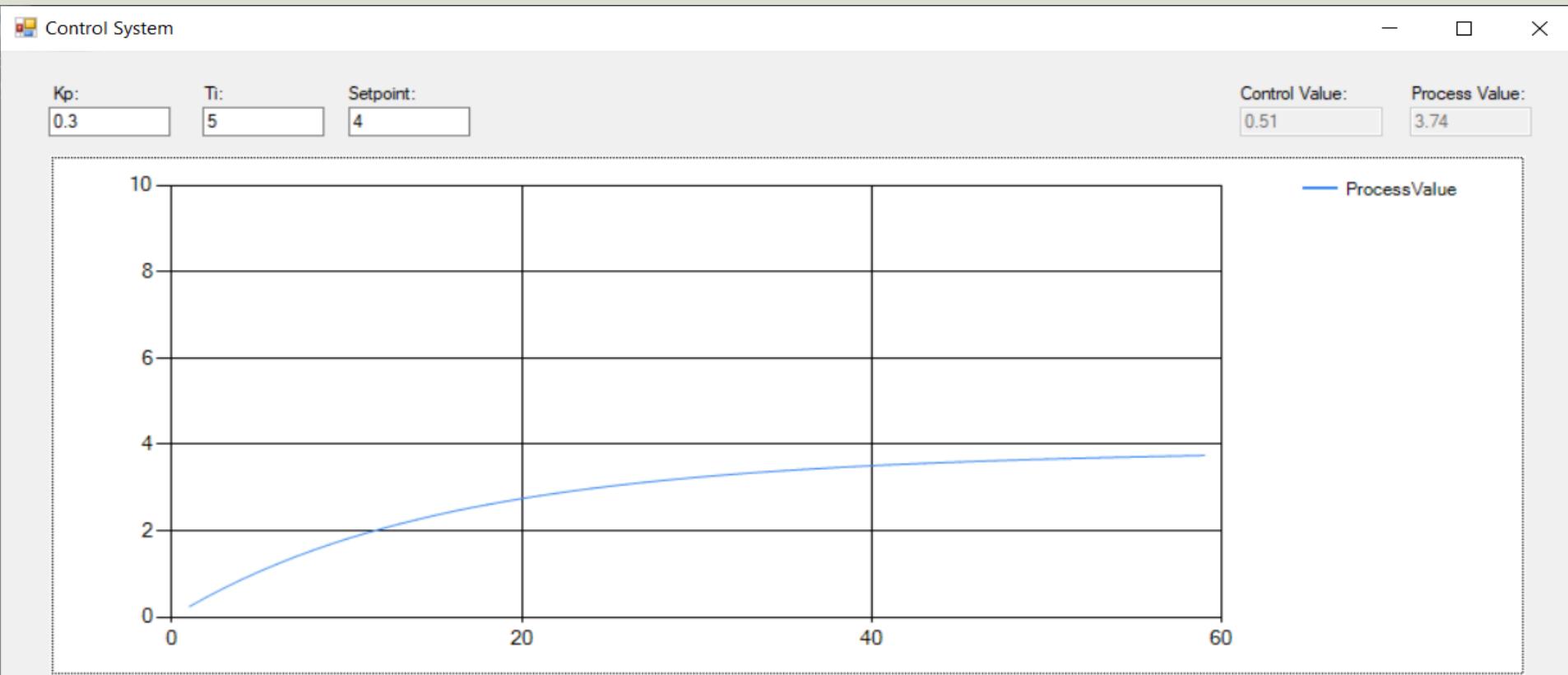
$$u_k = K_p e_k + \frac{K_p}{T_i} z_k$$

$$z_{k+1} = z_k + T_s e_k$$

Improvement

- Possible to set Reference Value (r) from GUI
- Possible to set K_p and T_i from GUI
- Plot Control Value
- Add Units
- Improve GUI in general
- Add separate Classes for Controller, etc.
- Etc.

WinForms App



C# Code

```
using System;
using System.Windows.Forms;
using System.Windows.Forms.DataVisualization.Charting;

namespace DynamicSystem
{
    public partial class Form1 : Form
    {
        double processValue = 0;
        double controlValue = 0;
        double Ts = 0.1;

        //PI Controller
        double Kp = 0.3;
        double Ti = 5;
        double r = 4;
        double u=0, z = 0;

        public Form1()
        {
            InitializeComponent();

            // Default Values
            txtKp.Text = Kp.ToString();
            txtTi.Text = Ti.ToString();
            txtR.Text = r.ToString();

            //Chart Initialization
            chartMeasurementData.Series.Clear();
            chartMeasurementData.Series.Add("ProcessValue");
            chartMeasurementData.Series["ProcessValue"].ChartType = SeriesChartType.Line;

            ChartArea areal = chartMeasurementData.ChartAreas[0];
            areal.AxisY.Minimum = 0;
            areal.AxisY.Maximum = 10;

            //Timer Initialization
            timerSimulationLoop.Interval = 1000;
            timerSimulationLoop.Start();
        }

        private void timerSimulationLoop_Tick(object sender, EventArgs e)
        {
            //Control System
            controlValue = PiController(processValue);
            processValue = DiscreteModel(processValue, controlValue);

            //Update GUI
            txtProcessValue.Text = processValue.ToString("0.##");
            txtControlValue.Text = controlValue.ToString("0.##");

            //Plot Data
            chartMeasurementData.Series["ProcessValue"].Points.AddY(processValue);
        }
    }
}
```

```
double DiscreteModel(double xk, double u)
{
    double a = 0.25; double b = 2; double xk1;

    xk1 = (1 - Ts * a) * xk + Ts * b * u;

    return xk1;
}

double PiController(double y)
{
    double e = r - y;
    u = Kp * e + (Kp / Ti) * z;
    z = z + Ts * e;

    return u;
}

private void txtKp_TextChanged(object sender, EventArgs e)
{
    Kp = Convert.ToDouble(txtKp.Text);
}

private void txtTi_TextChanged(object sender, EventArgs e)
{
    Ti = Convert.ToDouble(txtTi.Text);
}

private void txtR_TextChanged(object sender, EventArgs e)
{
    r = Convert.ToDouble(txtR.Text);
}
```

Summary

- We started to implement a Process Model
- Then we added a Timer and a Chart
- Then we added a PI Controller and a Control System
- There are still lots of Improvements to make, including improvements with Code, GUI and tuning the Control System, etc.
- The examples provided can be considered as a “proof of concept”
- The sample code is very simplified for clarity and doesn't necessarily represent best practices.

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